Integrating Sustainability Concepts Into Robotics Engineering Education at the **University of Michigan-Dearborn**

Introduction

- Sustainability concepts are very new to robotics education and research with almost no curricular initiative in the robotics engineering education domain that has addressed this very important field.
- At UM-Dearborn, we have developed ``Sustainability for Robotics'' and ``Robotics for Sustainability'' curriculum modules centered around mini-projects along the lines of **project-based learning** (PBL) philosophy.

Progress and Plan for Scaling Up

• Post-pilot expansion:

- Branching out to other courses (even nonrobotics courses, including ENG100 taught by Professor Delean Tolbert)
- Full support of the College of Engineering and Computer Science (CECS): "<u>And throughout</u> the college, there's a huge emphasis on project-based learning that helps students master both technical and non-technical <u>skills.</u>"
- Initiation of research efforts at the intersection of robotics engineering and sustainability (U-M Graham Sustainability Institute)



ENG100 taught by Professor Delean Tolbert







Cascaded use with

Battery technology playing an integral role The end-of-life of the autonomous delivery system becomes <u>an</u> input/raw material for another company/product? Analysis of "Reuse in Electric Vehicles" and "Cascaded Use in Stationary Applications". A project-based learning (PBL) experience for considering the elements of energy-efficiency, eco-friendliness, and socio-economic sustainability in last-mile delivery mobile robotic systems Sprinkling themes of JEDI-focused social Currently implemented in the course ECE 4641-Mobile Robots at UM-Dearborn Students have delivered two mini-projects on the designed PBL modules. Reuse with Be disassembled with clearly labeled materials for sourcing? Become an input/raw material for another company/product? How does closing of a company/industry impact a community/planet? The ideas have been pitched to all the participating faculty members at UM-Dearborn through the PBL-Palooza event at UM-Dearborn.



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Evaluation and Impact

• Evaluating the Impact:

A self-assessment form for the participating students with an emphasis on quantifying the likelihood of promoting the sustainability concepts/framework to the robotics/automation industries in Southeast Michigan (where most UM-Dearborn graduates start their careers in) after graduation.

Evaluating the Impact



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Procedure/Methods

Likely 45%





idea to impact



VENTUREWELL



ECE 3641 (Robotic Manipulators) ECE 543 (Kinematics, **Dynamics and Control** of Robots)

Courses on Mobile Robots) ECE 4641 (Mobile Robots) ECE 544 (Mobile Robots)

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EOP Framework Outcome	Equivalent ABET LO
 → Critical thinking (Leadership) → Design (Technical) → Environmental Impact Measurement (Technical) → Materials Choice (Technical) 	 1: an ability to identify, formulate, and solve complex engineering problems by applying principles of engineering, science, and mathematics 2: an ability to apply engineering design to produce solutions that meet specified needs with consideration of public health, safety and welfare, as well as global, cultural, social, environmental and economic factors
 → Critical thinking (Leadership) → Design (Technical) → Environmental Impact Measurement (Technical) → Materials Choice (Technical) 	4: an ability to recognize ethical and professional responsibilities in engineering situations and make informed judgments, which must consider the impact of engineering solutions in global, economic, environmental and societal contexts

References

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